### A Survey on Transfer Learning for Urban Spatio-temporal Machine Learning

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### Outline

- Introduction
- Urban Spatio-temporal Machine Learning
- Transfer Learning
- Urban Spatio-temporal Transfer Learning
  - Spatial Transfer Learning
  - Temporal Transfer Learning
  - Cross-modal Transfer Learning
- Conclusions and Future Work



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### Cities and Urban Problems

- Urbanization leads to many large cities
  - 54% population live in cities [UN, 2015]
  - Metropolises: New York, London, Tokyo, Hong Kong, etc.
- ...and also leads to important urban problems.
  - Environmental pollution
  - Energy consumption
  - Traffic management











### Machine Learning for Urban Problems

### • Triggers: Sensing and machine learning

- Smart sensors, GPS, etc. generate **spatio-temporal urban data.** 
  - E.g. Trajectories, social networks, environment sensors…
- Machine learning models capture spatio-temporal information.
  - Spatio-temporal machine learning (STML): Convolutional Neural Networks (CNN), Recurrent Neural Networks (RNN), Graph Neural Networks (GNN), ...

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- Applications:
  - Traffic: Speed, travel time, ...
  - Human activities: Human flow, events,
  - **Businesses**: Demand & supply, recommendation, …



### Data scarcity in cities

- Machine learning relies on big data.
  - More data leads to better performance.
- Data scarcity is common in cities.
  - Building new cities
  - Planning new urban services
- Problem: How to mitigate lack of data for urban STML?



New urban service: Tuen Ma Line, 2021



# Solution: Transfer Learning

- Transfer learning:
  - Key idea: Borrow knowledge from different but related tasks.
  - Effective in visual recognition, text mining, etc.
    - Pre-training & fine-tuning in computer vision
    - Cross-domain sentiment classification [Li, 2020].





[Pan et al. 2009]

• Q: How can transfer learning be applied to urban STML?





Cross-domain language analysis [Li, 2020]

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### Urban Spatio-temporal Machine Learning



**Q:** How is spatiotemporal information used to organize the data? Q: How to extract the spatio-temporal information within the data? **Q:** How to formulate urban computing tasks into machine learning problems?



### Urban Spatio-temporal Machine Learning: Data

• Data types in urban STML: Classified by **spatio-temporal correlations** 



Sequence: Trajectories [Wang et al. 2019a]

Data Type	Point	Sequence	Static Map	Static Graph	ST Map	ST Graph	
Temporal Variant?	No	Yes	No	No	Yes	Yes	
Spatial Variant?	No	Optional	Yes	Yes	Yes	Yes	Traject
Euclidean Spatial Corr.?	/	Optional	Yes	Optional	Yes	Optional	
Non-Euclidean Spatial Corr.	/	Optional	No	Yes	No	Yes	
Data Format	$\begin{array}{l}(l,t,a)\\a\in\mathbb{R}^{f}\end{array}$	$[(t_i, a_i)]_{i=1}^T \text{ or } \\ [(l_i, t_i, a_i)]_{i=1}^T \\ a_i \in \mathbb{R}^f$	$\mathbf{M} \in \mathbb{R}^{W \times H \times f}$	$G = (V, \mathbf{X}, \mathbf{A})$ $\mathbf{X} \in \mathbb{R}^{ V  \times f}$ $\mathbf{A} \in \mathbb{R}^{ V  \times  V }$	$\mathbf{M} \in \mathbb{R}^{T \times W \times H \times f}$	$G = (V, \mathbf{X}, \mathbf{A})$ $\mathbf{X} \in \mathbb{R}^{T \times  V  \times f}$ $\mathbf{A} \in \mathbb{R}^{T \times  V  \times  V }$	Co
Example	Incidents events	Weather data Trajectory	POI distribution	Road network	Regional air-quality	Traffic speed sensor readings	34.5
Models	Feature Engineering	RNN	CNN	GNN	CNN + RNN	GNN + RNN	34°N

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ST Maps: Urban Flow [Zhang et al. 2017]

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Converting Trajectories into Video-like Data



Graph: Traffic network [Yu et al. 2018]

### Urban Spatio-temporal Machine Learning: Data

- Multi-modal urban data:
  - e.g. Transport, environment, business [Zheng et al. 2014], etc.
- Leveraging multi-modal data is common in urban STML.
  - e.g. Use **road maps**, **points-of-interests** (POI), **weather**, and **transport** data to predict air quality [Wei et al. 2016a].





### Urban Spatio-temporal Machine Learning: Problems

- Supervised learning:  $\min_{f:\mathcal{X}\to\mathcal{Y}} \sum_{i=1}^{|D|} l(f(\mathbf{X}_i), y_i),$ 
  - Independent samples, label supervision.
  - Minimize loss function  $l(\hat{y}, y)$ 
    - Squared loss  $l(\hat{y}, y) = \|\hat{y} y\|^2$  for regression
    - Cross-entropy loss for classification  $l(\hat{y}, y) = -\sum y_i \log \hat{y_i}$



Converting Trajectories into Video-like Data

Urban flow forecasting [Zhang et al. 2017]

- Examples:
  - Forecasting:  $\mathbf{X} = (\mathbf{X}_{t-k} \dots \mathbf{X}_{t-1}), y = \mathbf{X}_t$
  - Estimation (e.g. Travel Time):  $\mathbf{X} = (\text{trajectory, metadata}), y = \text{travel time}$



### Urban Spatio-temporal Machine Learning: Models

- Models capture spatio-temporal relations.
- Spatial relations:
  - Convolutional Neural Nets (CNN): Euclidean, grid data.
    - **Convolution** and **pooling** capture relations within a k\*k grid.
    - Applications: Region flow forecasting [Zhang et al. 2017]
  - Graph Neural Nets (GNN): Non-Euclidean, network data
    - Aggregate information from irregular neighbors via edges.
    - Applications: Traffic forecasting [Geng et al. 2019]



Converting Trajectories into Video-like Data Deep Spatio-Temporal Residual Networks CNN for region flow forecasting [Zhang et al. 2017]



GNN for taxi demand forecasting [Geng et al. 2019]



### Urban Spatio-temporal Machine Learning: Models

- **Temporal** correlations:
  - Recurrent Neural Nets (RNN)
    - Inputs share a **memory** to remember previous observations.
- Hybrid Models
  - Jointly model spatio-temporal correlations.
  - Combine RNN with CNN/GNN.
  - e.g. DCRNN [Li et al. 2018] for traffic forecasting ConvLSTM [Shi et al. 2015] for precipitation.



DCRNN [Li et al. 2018]



ConvLSTM [Shi et al. 2015]

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# Transfer learning

- **Definitions** [Pan et al. 2009]:
  - **Domain**:  $\mathcal{D} = (\mathcal{X}, P(X))$ Feature space and feature distribution.
  - Task:  $\mathcal{T} = (\mathcal{Y}, P(y|X))$  Label space and label conditional distribution.



- Transfer learning: Improve learning on  $\mathcal{D}_T, \mathcal{T}_T$  using knowledge from  $\mathcal{D}_S, \mathcal{T}_S$  $\mathcal{D}_S \neq \mathcal{D}_T$  or  $\mathcal{T}_S \neq \mathcal{T}_T$
- Key Challenge: Identify domain-invariant knowledge.
- Categorization:
  - Homogeneous:  $\mathcal{X}_S = \mathcal{X}_T, \mathcal{Y}_S = \mathcal{Y}_T$
  - Heterogeneous:  $\mathcal{X}_S \neq \mathcal{X}_T$  or  $\mathcal{Y}_S \neq \mathcal{Y}_T$

# Transfer learning: Methods

- Transfer learning methods: "What to transfer"
  - Instance-based: Reuse source instances to train on the target domain.
  - Feature-based: Learn domain-invariant features for both domains and learn a common downstream model.
  - **Model-based**: Encode knowledge in model parameters and reuse parameters for the target domain.

Transfer Methodology	Key Assumption	Key Challenge	Categorization	Related Papers	Remarks
Instance-based	Some source samples are similar to target and can be reused.	Adequately re-weight source samples to train target model.	Non-inductive Inductive	[35, 36, 37] [38, 16]	
Feature-based	Source and target data share common latent factors.	Measure and maximize domain invariance of features.	Explicit (domain distance) Implicit (adversarial)	[39, 40, 41, 42] [43, 44, 45, 46]	MMD is a common distance metric.
Model-based	Model parameters encode common knowledge across domains.	Identify transferrability of model parameters.	Regularization Fine-tuning	[47, 48, 49] [50, 51, 30]	Fine-tuning popular in deep learning.



### Transfer learning: Instance-based

- Assumption: Some samples from source are similar to target.
- Key Challenge: Assign weights to source samples to train target model.
- Representative Method: TrAdaBoost [Dai et al. 2007].
  - Intuition:
    - Wrong target samples: Increase weight
    - Wrong source samples: Decrease weight (Likely dissimilar from target).
  - Method:
    - Source and target samples:  $D_S = \{X_i, y_i\}_{i=1}^n, D_T = \{X_j, y_j\}_{j=n+1}^{n+m}, y \in \{0, 1\}$

Sample weights 
$$\mathbf{w}^0 = [w_1^0, \dots, w_{n+m}^0]$$
. Source  
• Iterative Reweighting;  
 $w_i^{t+1} = \begin{cases} w_i^t \beta^{|h_t(X_i) - y_i|}, i \le n, \\ w_i^t \beta_t^{-|h_t(X_i) - y_i|}, n+1 \le i \le n+m. \end{cases}$   $0 < \beta, \beta_t < 1.$   
Target  
Target

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### Transfer learning: Feature-based

- Assumption: Domains share common latent factors.
- Challenge: Measure & minimize domain distance to identify common factors.
- Methods: Minimize Maximum Mean Discrepancy [Borgwardt et al. 2006]

$$\operatorname{MMD}\left(D_{S}, D_{T}\right) = \left\| \frac{1}{|D_{S}|} \sum_{i=1}^{|D_{S}|} \Phi_{K}\left(\mathbf{x}_{i}^{S}\right) - \frac{1}{|D_{T}|} \sum_{j=1}^{|D_{T}|} \Phi_{K}\left(\mathbf{x}_{j}^{T}\right) \right\|_{\mathcal{H}} , \quad Kernel \text{ function} \\ \mathcal{H}: \text{Kernel mapping of } K \\ \mathcal{H}: \text{KHS of kernel } K.$$

E.g. Transfer Component Analysis (TCA) [Pan et al. 2010]

Reformulation of MMD<sup>2</sup>

$$\min_{\mathbf{W}} \operatorname{tr}(\mathbf{W}^T \mathbf{K} \mathbf{L} \mathbf{K} \mathbf{W}) + \mu \operatorname{tr}(\mathbf{W}^T \mathbf{W})$$
  
s.t. $\mathbf{W}^T \mathbf{K} \mathbf{H} \mathbf{K} \mathbf{W} = \mathbf{I}$ 

# Transfer learning: Feature-based (Cont)

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- Methods: Minimize MMD
  - E.g. DDC [Tzeng et al. 2014]
    - Apply MMD regularization on the output features
    - Jointly minimize classification loss and MMD.
- Methods: Adversarial learning
  - Intuition: Domain invariant features should be
    - **1.** Discriminative w.r.t. labels
    - **2.** Indiscriminative w.r.t. source VS target domain
  - DANN [Ganin et al. 2016]
    - Feature Extractor G, Classifier C, Domain classifier D.
    - Minimize label loss  $l_y(G, C)$ : Intuition 1
    - Maximize domain loss  $l_d(G, D)$ : Intuition 2

$$\min_{G,C} \sum_{D} V(G,C,D) = \frac{1}{n_s} \sum_{i=1}^{n_s} l_y^i(G,C) - \lambda \left( \frac{1}{n_s} \sum_{i=1}^{n_s} l_d^{i,s}(G,D) + \frac{1}{n_t} \sum_{i=1}^{n_t} l_d^{i,t}(G,D) \right),$$





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### Transfer learning: Model-based

- Assumption: Model parameters encode general data structures.
- Key Challenge: Find transferrable parameters.
- Methods:
  - Train transferrable parameters with regularization
    - e.g. MT-SVM [Evgeniou and Pontil, 2004]
  - Identify transferrable parameters from well-trained models
    - [Yosinski et al. 2014]: Initialize from well-trained models improve generalization.
    - Fine-tuning: common in deep learning
    - CV: ImageNet pre-training.
       NLP: BERT [Devlin et al. 2019], GPT-3 [Brown et al. 2020] ...





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# Urban Spatio-temporal Transfer Learning

- When to apply, what to transfer in urban STTL?
  - Planning for new cities.
    - Transfer from existing cities: **spatial STTL**.
  - Planning for new urban services.
    - Transfer from existing urban services: cross-modal STTL.
  - Data evolution.
    - Adapt previous knowledge to the present: temporal STTL.



Development in Greater Bay Area: Spatial STTL





Adaptation to COVID-19: **Temporal STTL** [ICAO, 2020]

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# Urban Spatio-temporal Transfer Learning

#### • Key Challenges:

- Follows from urban STML & transfer learning.
- Common **spatio-temporal** patterns
- Common **multi-modal** knowledge



### Spatial STTL

#### • Formulation:

- Target: city with limited data
- Source: city with abundant data of the same type
- Homogeneous TL:  $P(X)_S \neq P(X)_Y$  or  $P(y|X)_S \neq P(y|X)_T$ 
  - Differences in urban layout, etc.
- Coarse VS Fine-grained methods:
  - **Coarse**-grained methods: Treat each city as a whole and apply transfer learning
  - Fine-grained methods: Divide cities as small regions. Find similar region pairs and transfer between them.



# Spatial STTL: Coarse-grained

- Feature-based: Extract features and project into common space.
  - Commonly **multi-modal** features: POI, land usage, transportation, etc.

CoFA [Liu et al. 2018a]

- Problem: Inferring dockless bike distribution
- Transfer method: Factor Analysis,

 $\mathbf{H}_{s:t}^*, \mathbf{W}^*, \mu^* = \arg\min_{\mathbf{H}_{s:t}, \mathbf{W}, \mu} \|\mathbf{M}_{s:t} - \mathbf{W}\mathbf{H}_{s:t} - \mu\|_F^2,$ 

• Project original features into a unified feature space by **minimizing reconstruction error**.



[Pang et al. 2020] and [He et al. 2020]

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- Problem: Inferring human mobility in new cities
- Transfer method: TCA [Pan et al. 2010]



(a) Trajectories of Source Cities (b) SC Feature Extraction (c) Domain Generalization (d) Mobility Intention Model

# Spatial STTL: Coarse-grained (Cont)

- Model-based methods: Train a model on source, re-use on target.
  - Two parts of models: general VS city-specific.

PR-UIDT [Ding et al. 2019]

- **Problem**: Cross-city, cross-user POI recommendation
- Transfer method: Regularization
  - Split both user and POI embeddings into general and non-local parts.
  - Regularize on the non-local part.





# Spatial STTL: Fine-grained

- Transfer may lead to higher error than non-transfer:
  - **Negative Transfer**: when domains differ a lot.
  - e.g. DC → NYC.
     DC is far less populated than NYC.
- Solution: Fine-grained methods
  - Idea: Cities may be dissimilar, but they must have similar parts (e.g. residential areas, business areas). These parts share common knowledge.
  - Methodology: Divide-and-match
    - Divide cities into smaller regions.
    - Obtain similar region pairs.
    - Transfer between similar regions instead of whole cities.

#### [Wang et al. 2019b] D.C.→Chicago Chicago→D.C. D.C.→NYC NYC→D.C. 1-day 3-day 1-day 3-day 1-day 3-day 1-day 3-day **Target Data Only** ARIMA 0.7400.694 0.707 0.661 0.360 0.341 0.707 0.661 0.350 0.359 DeepST 0.771 0.711 1.075 0.767 1.075 0.767 0.376 ST-ResNet 0.914 0.703 0.869 0.738 0.349 0.869 0.738 Source & Target Data 0.713 DeepST (FT) 0.652 0.611 0.672 0.619 0.363 0.369 0.711 0.385 ST-ResNet (FT) 0.695 0.623 0.349 0.667 0.615 0.696 0.691

# Spatial STTL: Fine-grained

- Option 1: Using **fixed** similarity of **raw features** *M<sub>s</sub>*, *M<sub>t</sub>*.
  - Compute region-wise similarity  $\rho_{r_s,r_t}$ .
  - Minimize domain distance for matched regions  $\Delta = \{(r_t, r_s), \forall r_t\},\$

CityTransfer [Guo et al. 2018]

- Problem: Cross-city site recommendation
  - Similarity Measure: Pearson correlation
  - Train autoencoder f to minimize

$$\sum_{(r_t, r_s) \in \Delta} \rho_{r_t, r_s} \| f(\mathbf{M}_{r_s}) - f(\mathbf{M}_{r_t}) \|^2$$

and use  $f(M_s)$ ,  $f(M_t)$  for recommendation.



RegionTrans [Wang et al. 2019b]

- **Problem**: Spatio-temporal forecasting
  - Similarity Measure: Cosine similarity
  - Pre-train CNN-LSTM  $f_2(f_1(x))$  on source.
  - Fine-tune  $f_2(f_1(x))$  on target:

$$\sum_{r_t} \|y_{r_t} - f_2(f_1(x_{r_t}))\|^2 + \sum_{\substack{(r_s, r_t) \in \Delta \\ \text{Matched domain} \\ \text{distance}}} \rho_{r_s, r_t} \|f_1(x_{r_t}) - f_1(x_{r_s})\|^2$$

# Spatial STTL: Fine-grained (Cont)

• Option 2: Using trainable similarity of output features.

 $\rightarrow \hat{y}_{r_c,k_c}$ 

MetaST [Yao et al. 2019]

- Problem: Spatio-temporal forecasting.
- Methods: Transfer attention values
  - Cluster source regions using k-means
  - Set memory  $M \in \mathbb{R}^{k \times f}$  for each cluster.
  - For source region  $r_c$ , use output  $h_{r_c,k_c}$  to query M, get weights  $p_{r_c,k_c}$ . Match  $p_{r_c,k_c}$  with its cluster id.
  - Use attention output  $z_{r_c,k_c}$  as complement features for target regions.

ST-Mem  $p_{r_c,k_c}$ 

WANT [Liu et al. 2019]

- **Problem**: Cross-city site recommendation
- Methods: Transferability re-weighting.
  - Architecture: DANN [Ganin et al. 2016]
  - Weight each source sample with target via:
    - **Domain similarity**: According to *D*.
    - **Data quality**: According to (*G*, *C*).
  - Minimize weighted DANN loss:

$$\min_{G,C} \max_{D} V(G,C,D) = \frac{1}{n_s} \sum_{i=1}^{n_s} w_i b_y^i(G,C) - \lambda \left( \frac{1}{n_s} \sum_{i=1}^{n_s} w_i b_d^{i,s}(G,D) + \frac{1}{n_t} \sum_{i=1}^{n_t} l_d^{i,t}(G,D) \right),$$

# Spatial STTL: Fine-grained (Cont)

#### • Summary of fine-grained methods

Related Work	Task	Matching Data	Matching Metric	Trainable Matching
[Wang et al. 2019b]	Spatio-temporal	Raw features	Cosine Similarity	No
[Yao et al. 2019]	Forecasting	Output features	Implicitly via Attention	Yes
[Guo et al. 2018]	Cross-city site	Raw features	Pearson correlation	No
[Liu et al. 2021]	recommendation	Output features	Implicitly via domain and label classifier	Yes

- Raw feature matching:
  - Pro: Stable. Incorporates multi-modal information.
  - Con: Performance relies on quality of features.
- Output feature matching;
  - Pro: Flexible, trainable matching.
  - **Con**: Limited target data  $\rightarrow$  overfit.



[Wang et al. 2019b] Check-in (auxiliary) is related to crowd flow (limited).

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# Temporal STTL

- Temporal STTL tackles data distribution shifts.
  - Two kinds of distribution shifts
- Formulation:
  - Homogeneous TL
  - Source: Previous periods
  - Target: Current period





Long-term (monthly) changes

**Sudden changes,** e.g. holiday [Zhang et al. 2017]

- . 2017] [Karacasu et al. 2011]
- Related Concept: Continual learning [Chen and Liu, 2018].
  - A series of domains and tasks  $\mathcal{D}_i, \mathcal{T}_i, i = 1 \dots N$ ,
  - For each n, learn task  $\mathcal{T}_n$  with knowledge from  $\mathcal{T}_i, i < n$  .
  - In temporal STTL, each timestamp defines a task.



### Temporal STTL for Indoor Localization

- Indoor localization: signal strength  $\mathbf{s} = (s_1, \dots s_m) \rightarrow \text{ location } (x, y)$
- Temporal TL for indoor localization:
  - **Goal**: At  $t_k$ , adapt  $f_1$  to  $f_k$  using  $\{\mathbf{s}_{ki}, l_{ki}\}_{i=1}^l$ ,  $\{\mathbf{s}_{kj}\}_{j=l+1}^{l+u}$
  - The first *l* labeled data are from **fixed** positions: **Reference points.**
- Feature-based method: LeManCoR [Pan et al. 2007]
  - Localization with extended Manifold Co-Regularization
  - Assumption: Models from different times agree on reference points.

$$f_{1}^{*}, f_{k}^{*} = \arg\min_{f_{1} \in H_{K_{1}}, f_{k} \in H_{K_{k}}} \frac{\mu}{l_{1}} \sum_{i=1}^{l_{1}} V(\mathbf{s}_{1i}, l_{1i}, f_{1}) + \gamma_{A}^{(1)} \|f_{1}\|_{H_{K_{1}}} + \gamma_{B}^{(1)} \|f_{1}\|_{I} \\ + \frac{1}{l} \sum_{i=1}^{l} V(\mathbf{s}_{ki}, l_{ki}, f_{k}) + \gamma_{A}^{(2)} \|f_{k}\|_{H_{K_{k}}} + \gamma_{B}^{(2)} \|f_{k}\|_{I} + \frac{\gamma_{I}}{l} \sum_{i=1}^{l} [f_{1}(\mathbf{s}_{1i}) - f_{k}(\mathbf{s}_{ki})]^{2}, |f|_{I}: \text{ Complexity regularization}$$

# Temporal STTL for Indoor Localization (Cont)

- Model-based method: TrHMM [Zheng et al. 2008]
  - Transferring Hidden Markov Models:  $(L, O, \lambda, A, \pi)$ 
    - L, O: Location & observation space
    - $\lambda = P(o|l) = N(\mu, \Sigma), l \in L, o \in O$
    - A: Transition matrix between locations L.  $\pi$ : Initial distribution over L



- Assumption: Fixed relations between reference (r) and other points (k) across t.
- Method:
  - 1. Estimate  $\lambda_1$  at time  $t_1$ .
  - 2. Obtain relations between reference and other points via regression.

$$s_j^k = \alpha_{0j}^k + \alpha_{1j}^k r_{1j} + \dots \alpha_{lj}^k r_{lj} + \varepsilon_j,$$

3. At time *t*, **re-use** the **regression** model to reconstruct data, and **fine-tune**  $\lambda_t$  $\mu_t = \beta \mu_1 + (1 - \beta) \mu_t^{reg}$ ,

$$\Sigma_t = \beta (\Sigma_1 + (\mu_t - \mu_1)(\mu_t - \mu_1)^T) + (1 - \beta) (\Sigma_t^{reg} + (\mu_t - \mu_t^{reg})(\mu_t - \mu_t^{reg})^T)$$

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### Cross-modal STTL

- Two scenarios of cross-modal STTL:
  - Missing feature modality:
    - e.g. Predict air quality using **road maps**, **POI, weather**, and **transport** data transport data is missing in a city.
    - Solution: Learn the relation between existing modalities and the missing one.
    - Heterogeneous TL:  $\mathcal{X}_S 
      eq \mathcal{X}_T$
  - Missing label modality:
    - e.g. Detect ride-sharing car trajectories with **no labeled trajectories**.
    - Solution: Find related data (e.g. taxis), and link source labels with target ones.
    - Heterogeneous TL:  $\mathcal{Y}_S 
      eq \mathcal{Y}_T$



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Air Quality

**Example: Predicting air quality** 

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 $\mathbf{D}_2$ 

 $\mathbf{D}_1$ 

# Cross-modal STTL: Missing feature modality

- FLORAL [Wei et al. 2016a]
  - Assumption: Relations between modalities are invariant across domains.
  - Key Idea: Extract and transfer such relations
  - Methods:
    - Relation encoding: Build sample-modality graph Nodes: Each sample in each modality Intra-modality edges: feature distance Inter-modality edges: sample proximity
    - **Relation learning:** Cluster sample-modality graph. Each cluster forms **base vectors** in **dictionaries**.
    - Transfer: Share dictionaries across domains Sparse coding to obtain domain-invariant features. Multi-modal TrAdaBoost to reweight modalities.



### Cross-modal STTL: Missing label modality

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- CoHTL [Wei et al. 2016b]
  - Target: sensor data with few labels. Source: Social messages
  - Key Idea: Link samples & labels from social messages to sensors.
  - Methods:
    - Label linking: Topic model & word embedding.
    - Sample linking: Spatio-temporal proximity.
    - Feature-based transfer: Link regularization.

 $\mathcal{O} = \left\| \mathbf{P} - \mathbf{U} \mathbf{V}_1 \|_F^2 + \| \mathbf{Q} - \mathbf{W} \mathbf{V}_2 \|_F^2 \right\|_F$ Reconstruction error Example of spatio-temporal sample linking Sequences and the sample linking sample linking sample linking sample links ( $S_{ij}$ ).

eatexercisetravelhave<br/>dinnergo<br/>outdoorbreak-<br/>fastexercisebuy<br/>tickets

Results of label linking by word embeddings.



# Summary of urban STTL

- Spatial: Homogeneous TL
  - **Coarse** VS **Fine**-grained methods: transfer between **similar** parts
- Temporal: Homogeneous TL,
  - **Example:** Temporal STTL for indoor localization (via reference points)

#### • Cross-modal: Heterogeneous TL

- **Cases:** Missing feature/label modality
- Key: Relations between modalities.

Urban	Existing	Common ST Patterns				Common Multi-modal Knowledge				
STTL	Works	Coarse-	grained	Fi	ne-grained	đ	Feature	Computing	Sparse	Co-
Setting	WOIKS	Feature	Model	Instance	Feature	Model	Concatenation	Similarity	Coding	training
	Liu et al. [63]	$\checkmark$					✓			
	Liu et al. [64]	$\checkmark$					$\checkmark$			
	Pang et al. [65]	$\checkmark$					$\checkmark$			
	He et al. [66]	$\checkmark$					$\checkmark$			
	Li et al. [67]	$\checkmark$								
	Ding et al. [68]		$\checkmark$							
Spatial	Wang et al. [69]		$\checkmark$							
Transfer	Wang et al. [70]				$\checkmark$	$\checkmark$		$\checkmark$		
Learning	Yao et al. [71]					$\checkmark$				
	Song et al. [72]				$\checkmark$	$\checkmark$		$\checkmark$		
	Mallick et al. [73]					$\checkmark$				
	Guo et al. [74]				$\checkmark$		$\checkmark$	$\checkmark$		
	Liu et al. [75]			$\checkmark$	$\checkmark$		$\checkmark$			
	Wang et al. [22]			$\checkmark$	$\checkmark$		$\checkmark$			
Temporal	Pan et al [55]	ĺ			<u> </u>					
Transfer	Zheng et al. [76]				•	$\checkmark$				
Learning	Zhong et ul. [70]					•				
Cross-modal	Wei et al. [77]			$\checkmark$	$\checkmark$				$\checkmark$	
Transfer	Wang et al. [78]			$\checkmark$		$\checkmark$				$\checkmark$
Learning	Wei et al. [79]				$\checkmark$			$\checkmark$		



### Conclusion

- Motivation: Urban computing + machine learning meets lack of data.
- Challenge: Common ST patterns & Common multi-modal knowledge
- Categorization: Spatial, temporal and cross-modal
- Future directions:
  - Transfer learning with **effective multi-modal fusion**:
    - Existing works mainly use feature concat or feature similarity.
  - Transfer learning with **dynamics**:
    - Temporal STTL with detection of data shifts.
    - Adaptive knowledge transfer at different periods.
  - Transfer learning with **privacy** 
    - Spatio-temporal data may contain user privacy.



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